

# **FUN3D v12.4 Training**

## **Session 8: Parameterization Tools**

Bill Jones



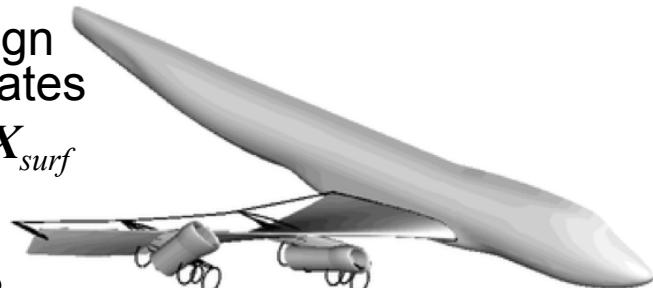
<http://fun3d.larc.nasa.gov>

FUN3D Training Workshop  
March 24-25, 2014



# Setting

- FUN3D shape design relies on a pre-defined relationship between a set of parameters, or design variables, and the discrete surface mesh coordinates
- Given  $DV$ , surface parameterization determines  $X_{surf}$ 
  - For example, given the current value of wing thickness at a location, what are the corresponding xyz-coordinates of the mesh?
- This narrows down the number of design variables from hundreds of thousands (raw mesh points) to dozens or hundreds
  - Optimizers will perform more efficiently
  - Smoother design space
- An additional requirement of the parameterization package is that it provides the Jacobian of the relationship between the design variables and the surface mesh,  $\partial X_{surf} / \partial DV$
- While users may provide their own parameterization scheme, FUN3D is set up to handle three common packages:
  - MASSOUD: Aircraft-centric design variables (thickness, camber, planform, twist, etc)
  - BandAids: General FFD based tool
  - Sculptor<sup>®</sup>: Commercial package from Optimal Solutions



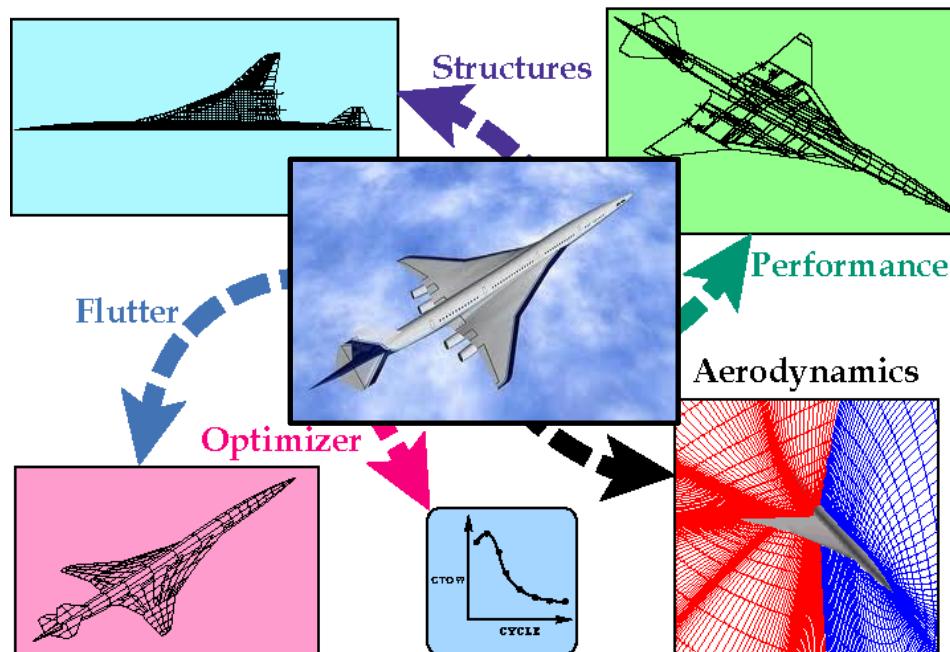
# Learning Goals

- Parameterize geometry with respect to DVs to control shape
  - MASSOUD
  - BandAids
- Generate perturbed surface mesh and SDs for FUN3D design
  - Visual validation
- What we will *not* cover
  - Body transformations
  - How to use the data in FUN3D
    - That will be covered in the next session



# MASSOUD

- Multidisciplinary Aerodynamic-Structural Shape Optimization Using Deformation
  - AIAA-2000-4911 (Jamshid Samareh)
- Used to generate consistent models for MDAO
  - Same shape changes communicated across all disciplines
- Highly tailored for aerodynamic shapes
  - Parameters familiar to engineer
- Mesh based parameterization



# MASSOUD Key Ideas

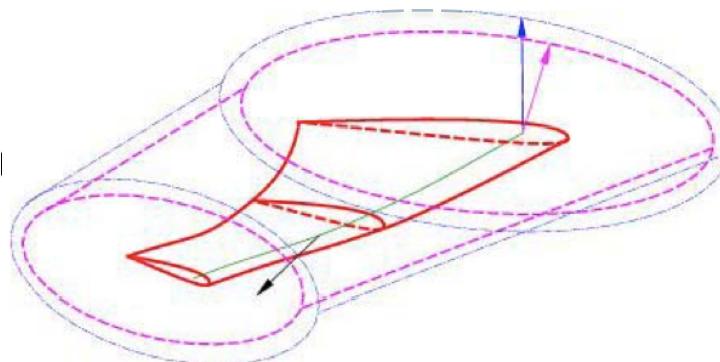
1. Uses soft object animation algorithms for deforming meshes
  - Nonlinear global deformation (twist and dihedral)
  - NURBS surface (camber and thickness)
  - Free-form deformation (planform)
2. Parameterizes the discipline meshes
  - Avoids mesh regeneration
3. Parameterizes the changes in shape, not the shape itself
  - No need to reproduce shape
    - Reduces the number of design variables



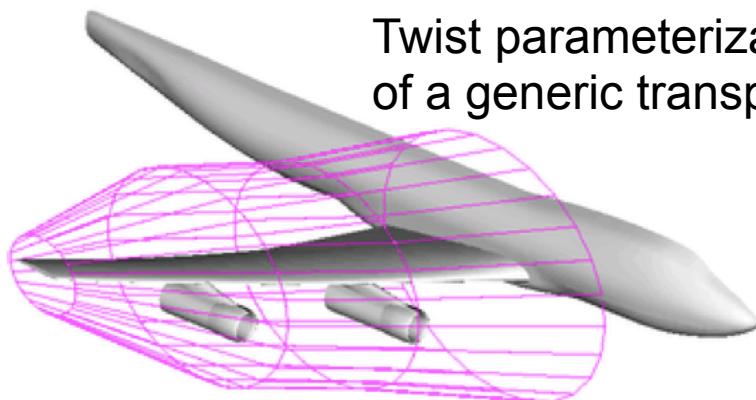
# MASSOUD Twist and Shear

- Nonlinear Global Deformation
  - Wrapped in twist cylinder
    - Twisted and sheared in planes along span normal to twist vector

Twist parameterization  
of a generic wing



Twist parameterization  
of a generic transport

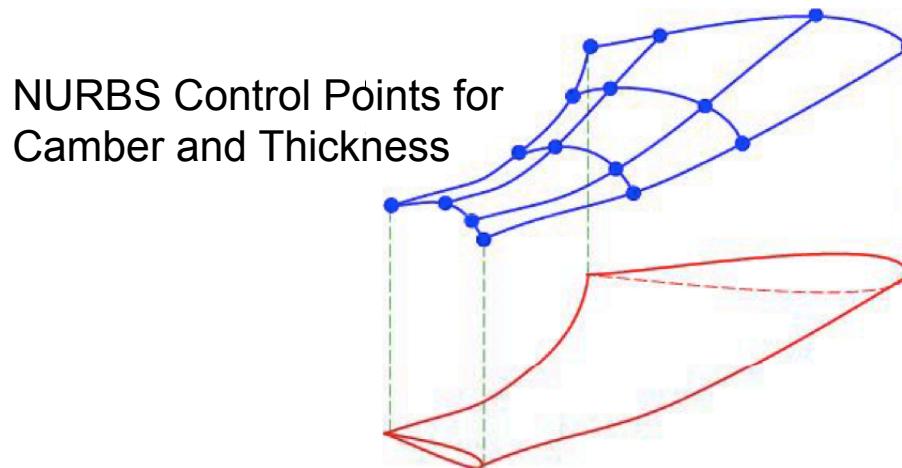


Extreme deformation  
of a generic transport

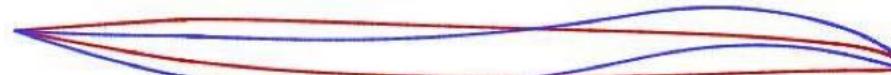


# MASSOUD Camber and Thickness

- Non-Uniform Rational B-Spline (NURBS)
  - Represents the shape changes not the shape

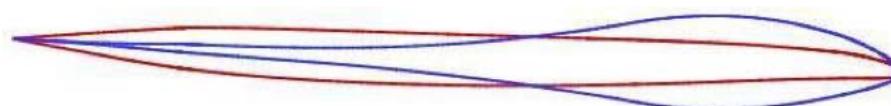


Camber



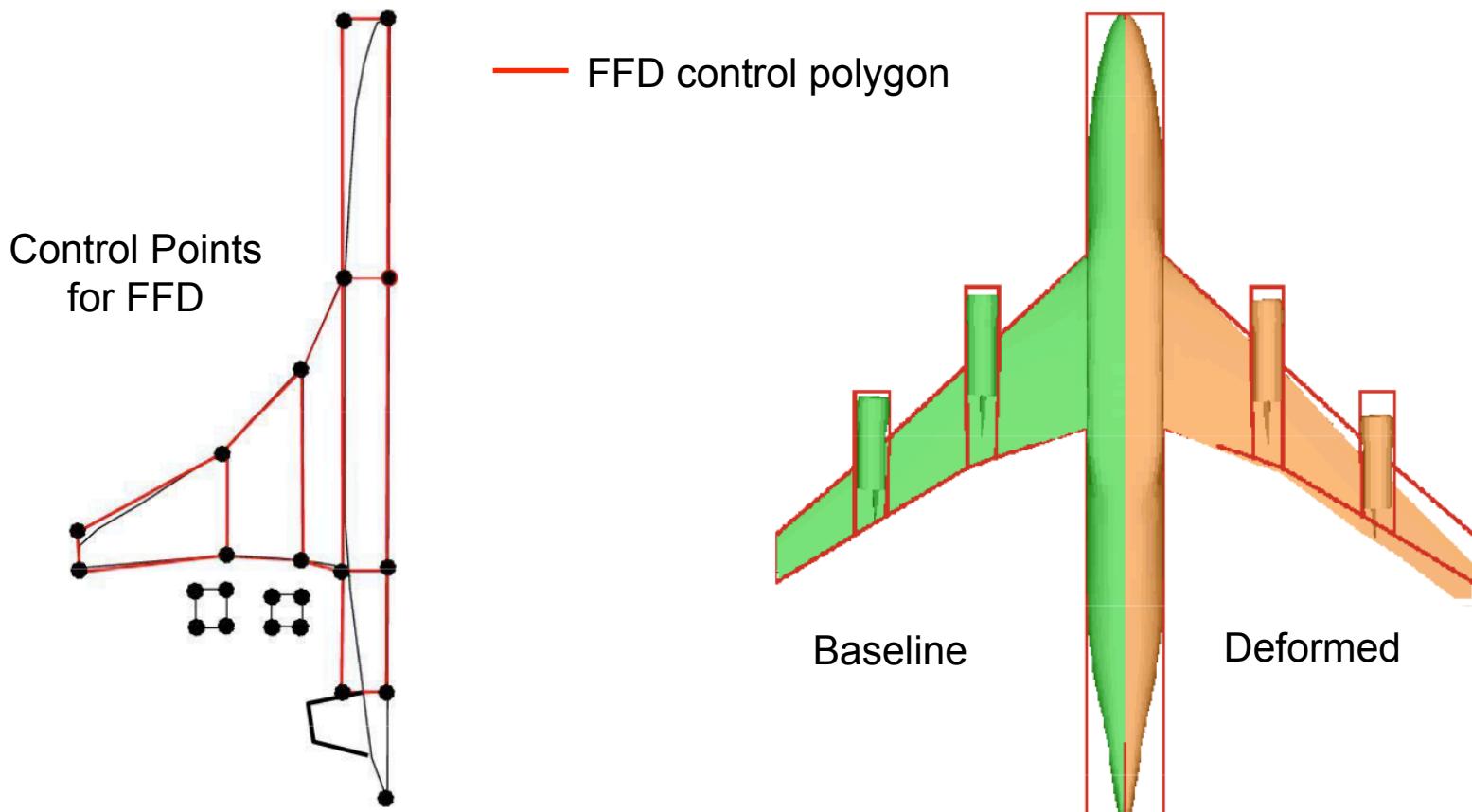
Extreme Camber and Thickness deformation

Thickness



# MASSOUD Planform

- Free-form Deformation (FFD)
  - Surround shapes with quadrilaterals

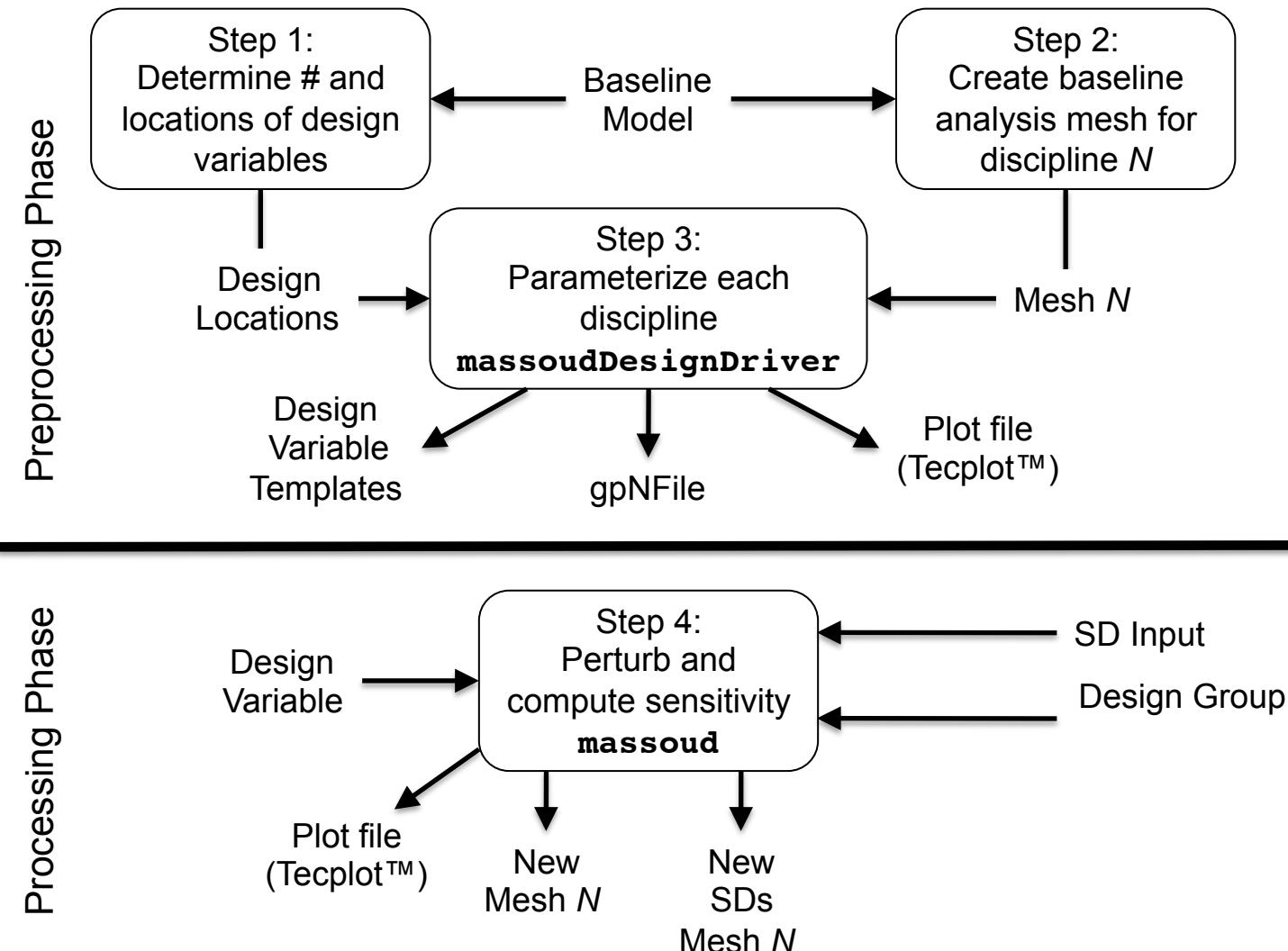


# MASSOUD Installation

- Distributed as source code
  - Single **Makefile** uses GNU C compiler (**gcc**)
    - Any localization must be done manually
  - Creates two executables
    - `massoudDesignDriver` creates parameterization
    - `massoud` surface mesh perturbation with sensitivity data



# MASSOUD Process



# MASSOUD Step 1

- Parameterization requires input to define DV locations
  - Small ASCII file
  - Contains 7 groups of oriented curves
    - X axis is positive downstream
    - Y is positive out the wing span
      - Y should be positive with curves monotonically increasing
  - GridTool can be used to create the file



# MASSOUD Design Locations File

Design location file Case Name Title (SECTION 1)

np ne ntwist ncmax  
4 1 2 100 0 1 2

Pt	X	Y	Z (SECTION 2)
0	-0.0010000	-1.0010000e+00	0.0000000e+00
1	1.0010000	-1.0010000e+00	0.0000000e+00
2	1.0010000	0.0000000e+00	0.0000000e+00
3	-0.0010000	0.0000000e+00	0.0000000e+00
0	1	2	3

Planform

#Twist Vector (SECTION 3)

#	Ax	Ay	Az		
	0.0000000e+00	1.0000000e+00	0.0000000e+00		
#	x	y	z	ir	or
2.5000000e-01	-1.0000000e+00	0.0000000e+00	1000.0	10000.0	
2.5000000e-01	0.0000000e+00	0.0000000e+00	1000.0	10000.0	

Twist

# Le/Te definitions (SECTION 4)

2		
0.0000000e+00	-1.0010000e+00	0.0000000e+00
0.0000000e+00	0.0000000e+00	0.0000000e+00
2		
1.0000000e+00	-1.0010000e+00	0.0000000e+00
1.0000000e+00	0.0000000e+00	0.0000000e+00

Leading and  
Trailing Edges

5 2 0.000000e+00 -1.001000e+00 0.000000e+00 1.000000e+00 # Thickness (SECTION 5)

0.0	0.000000e+00	0.000000e+00
0.1	0.000000e+00	0.000000e+00
0.5	0.000000e+00	0.000000e+00
0.75	0.000000e+00	0.000000e+00
1.0	0.000000e+00	0.000000e+00

Thickness

3 2		
0.000000e+00	-1.001000e+00	0.000000e+00
0.000000e+00	-0.500000e+00	0.000000e+00
0.000000e+00	0.000000e+00	0.000000e+00

Camber

5 2 0.000000e+00 -1.001000e+00 0.000000e+00 1.000000e+00 # Camber (SECTION 6)

0.0	0.000000e+00	0.000000e+00
0.1	0.000000e+00	0.000000e+00
0.5	0.000000e+00	0.000000e+00
0.75	0.000000e+00	0.000000e+00
1.0	0.000000e+00	0.000000e+00

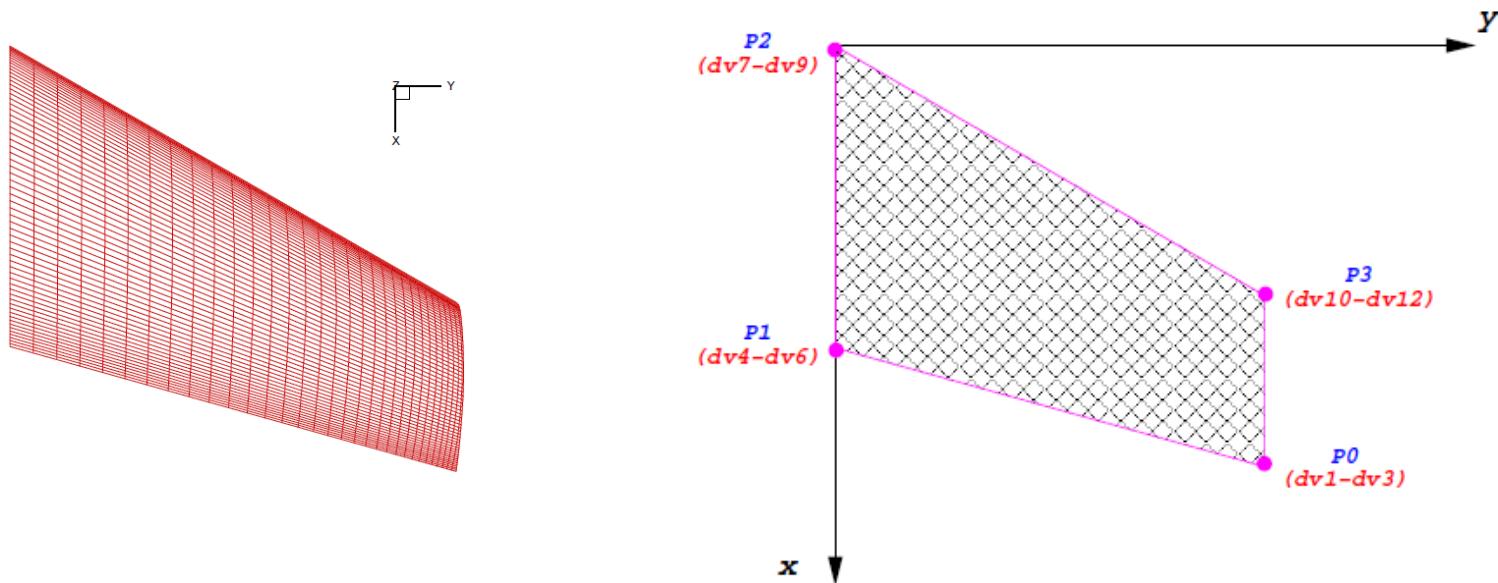
3 2		
0.000000e+00	-1.001000e+00	0.000000e+00
0.000000e+00	-0.500000e+00	0.000000e+00
0.000000e+00	0.000000e+00	0.000000e+00



# MASSOUD Design Locations

## 1. Planform

- Cover planform with 5 point quadrilaterals
  - Closed but orientation does not matter
- 1 Curve per planform section
- GridTool Family name “**planform**”



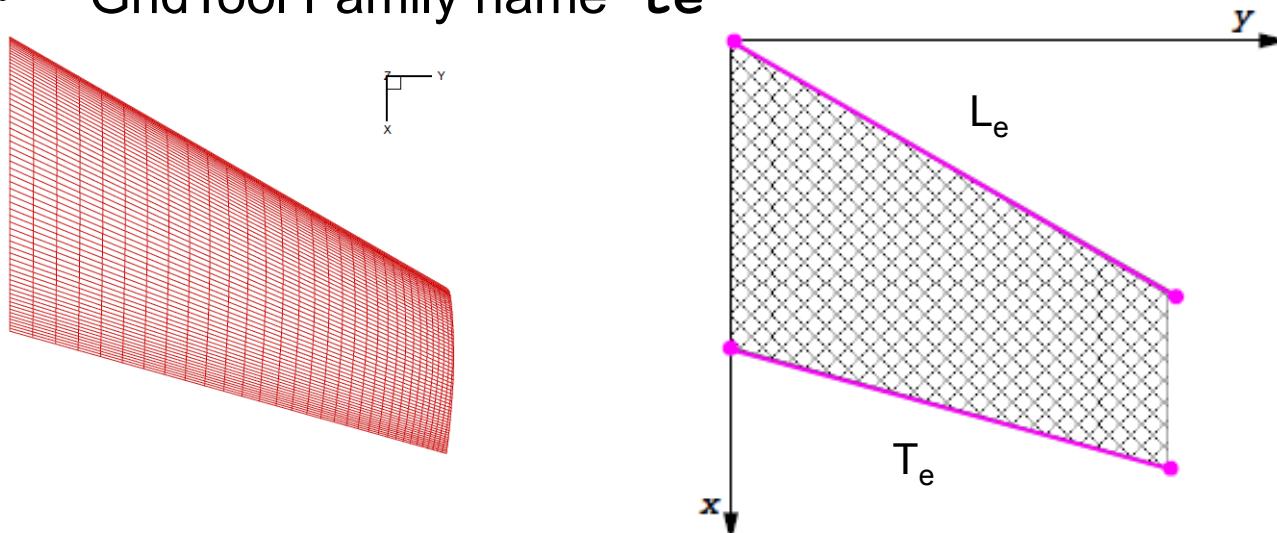
# MASSOUD Design Locations

## 2. Leading Edge

- Create an  $n$  point PWL curve defining the leading edge
  - Must bound all mesh nodes
  - May extend beyond actual geometry
- GridTool Family name “**le**”

## 3. Trailing Edge

- Create an  $n$  point PWL curve defining the trailing edge
  - Must bound all mesh nodes
  - GridTool Family name “**te**”



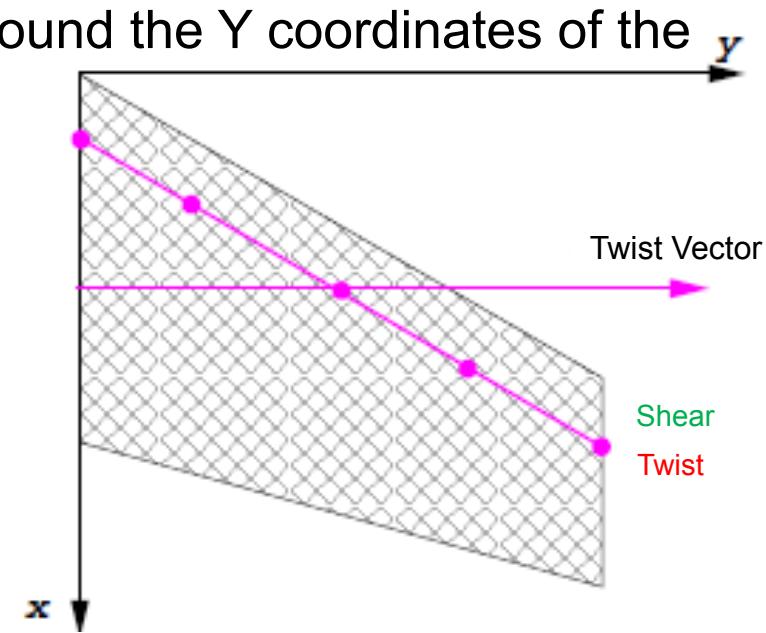
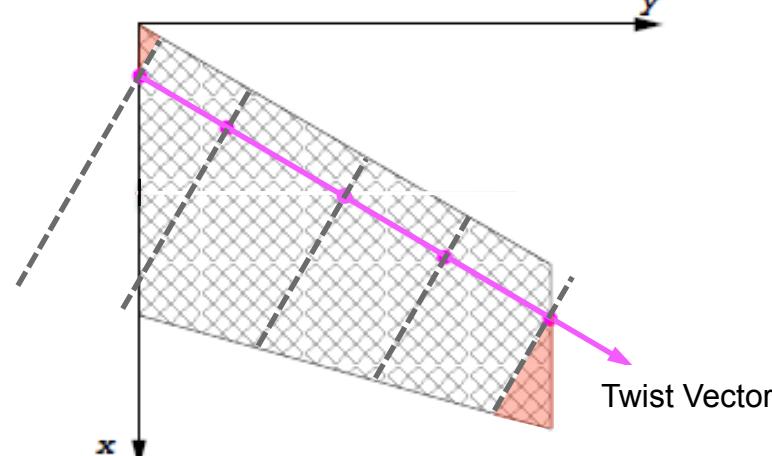
# MASSOUD Design Locations

## 4. Twist Vector

- Create a 2 point curve to represent the twist vector
  - Twist sections defined normal to this vector
- GridTool Family name “**twistv**”

## 5. Twist Location

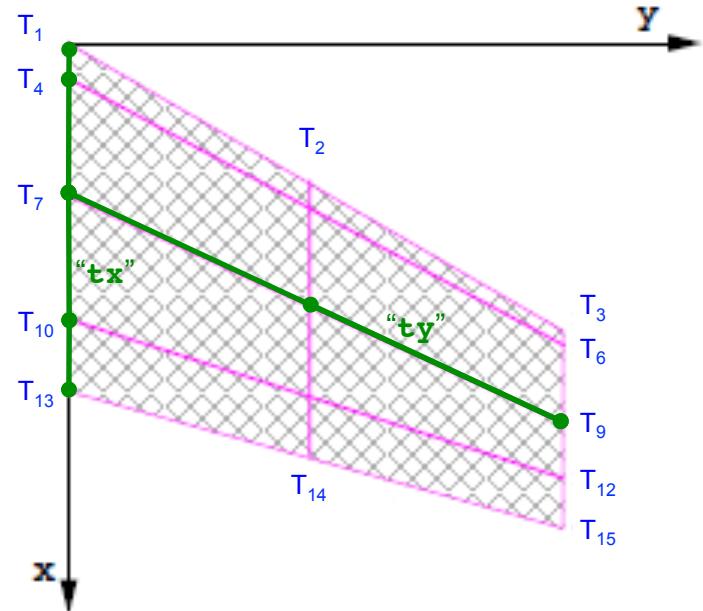
- Create an  $n$  point PWL curve to represent the  $n$  twist locations
- Airfoil sections defined at these points normal to “**twistv**”
  - First and last section must bound the Y coordinates of the target mesh
- GridTool family name “**twist**”



# MASSOUD Design Locations

## 6. Thickness

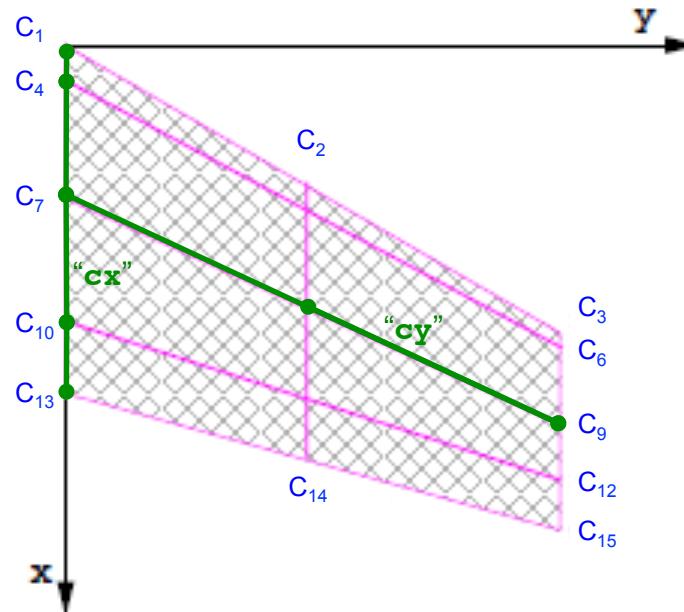
- Chordwise
  - Create an  $n$  point PWL curve to represent the  $n$  chordwise thickness locations
  - Start, length, and %
  - GridTool family name “**tx**”
- Spanwise
  - Create an  $m$  point PWL curve to represent the  $m$  spanwise thickness locations
  - Should bound Y values of all target mesh nodes
  - Beginning and ending Y coordinates must be bounded by the Y coordinates of both the “**le**” and “**te**” curves
  - May be a duplicate of the “**twist**” curve
  - GridTool family name “**ty**”
- $n \times m$  set of DVs



# MASSOUD Design Locations

## 7. Camber

- Same as for Thickness but with GridTool family names “**cx**” and “**cy**” respectively
- May be duplicates of “**tx**” and “**ty**”
- Two curves define  $n \times m$  set of DVs



# MASSOUD Step 2

- Dump out surface meshes of interest in a Tecplot™ format
  - Includes the surface node coordinates
  - Global ID of the surface nodes wrt the volume mesh
  - FUN3D flow solver CLO ‘**--write\_massoud\_file**’
    - Produces “[**project**]\_massoud\_bndryN.dat” file for body *N*
  - Default extracts all viscous boundary surfaces as separate bodies
- FUN3D Namelist controls

```
&massoud_output
    n_bodies = 2                      ! Parameterize 2 bodies
    nbndry(1) = 6                      ! 1st body has 6 boundaries
    boundary_list(1) = '3-8'            ! Boundaries in 1st body
    nbndry(2) = 3                      ! 2nd body has 3 boundaries
    boundary_list(2) = '9,10,12' ! Boundaries in 2nd body
    /
```

- **boundary\_list()** indices should reflect boundary *lumping*



# MASSOUD Step 3

- Generate geometry parameterization

```
% massoudDesignDriver -t input_massoud_bndry1.dat \
designLocations \
design.gp.1
```

- Geometry parameterization is output in “*design.gp.1*”
  - Used as input to ‘**massoud**’
- Additional output
  - “**designVariableTemplate**”
    - Reference for “**design.1**” file with zero perturbations
  - “**designTemplate.usd**”
    - Reference for “**design.usd.1**” user defined variable links
  - “**designVariableTemplateNumber**”
    - Lists the DV indices by DV type (planform, twist, etc.)
  - “**baselineShape.plt**”
    - Tecplot™ readable zero perturbation reference
  - Errors in “**GP.log**”



# MASSOUD Step 4

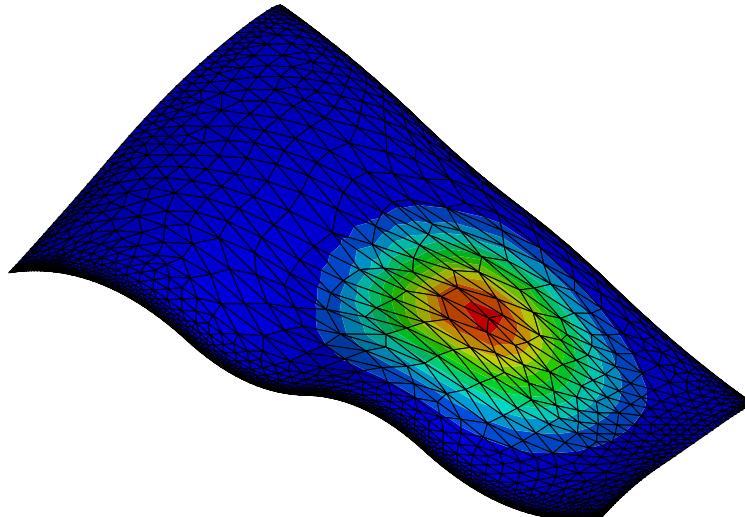
- Mesh deformation    % **massoud massoud.N**
  - Where MASSOUD input is in “**massoud.N**”
  - FUN3D design will utilize “**customDV.N**” for perturbations

```
#MASSOUD INPUT FILE
# Option (0 analysis), (> 0 sd using user dvs ) (-1, sd using massoud dvs)
-1
# core (0 incore solution) (1 out of core solution)
0
# input parameterized file
design.gp.1 ←
# design variable input file
design.1 ←
# input sensitivity file (used for Option > 0)
design.usd.1 ←
# output file mesh file
new1.plt
# output tecplot file for viewing
model.tec.1
# file containing the design variables group
designVariableGroups.1
# user design variable file
[customDV.1] ←
```



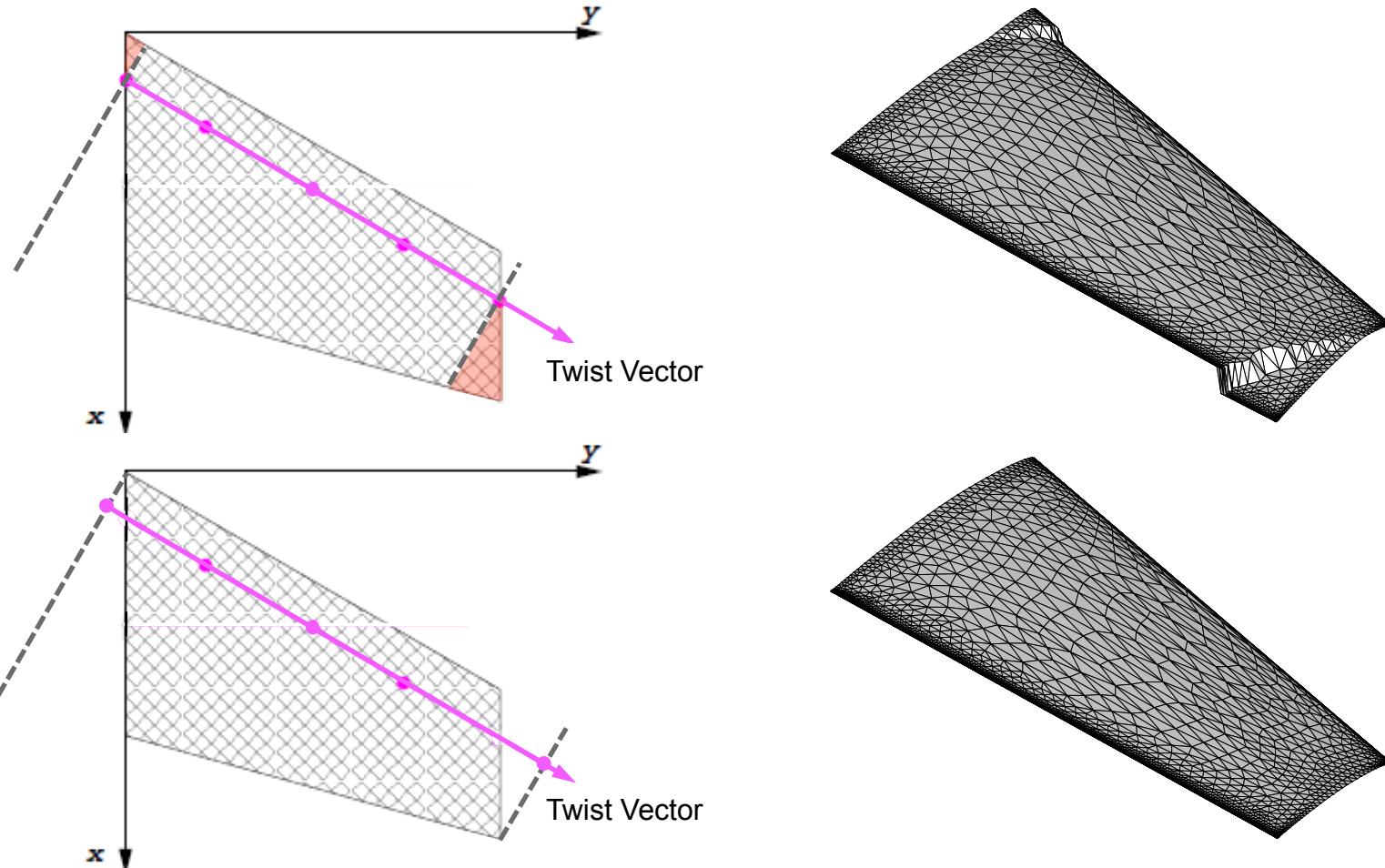
# MASSOUD Results

- Visual inspection
  - Tecplot™
    - “**model.tec.1.sd1**” contains mesh and SDs
      - (e.g. XD1, YD1, ZD1... XDndv, YDndv, ZDndv)
  - GridTool
    - **% GridTool –d model.tec.1.sd1**
    - Sliders to interactively perturb DVs
    - Twist is non-linear and is only indication of change



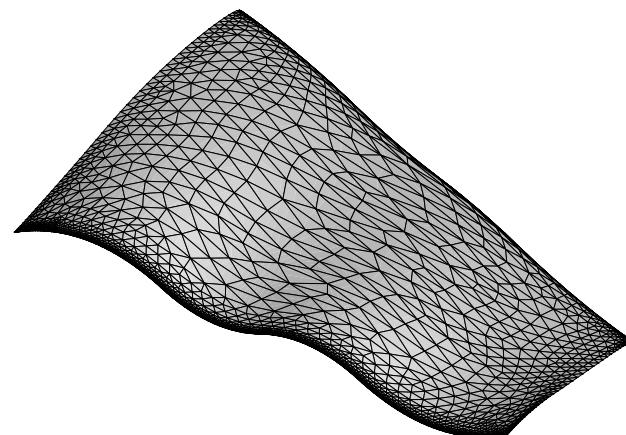
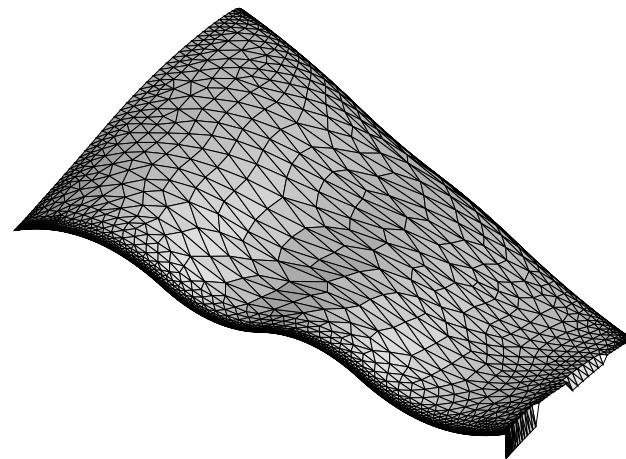
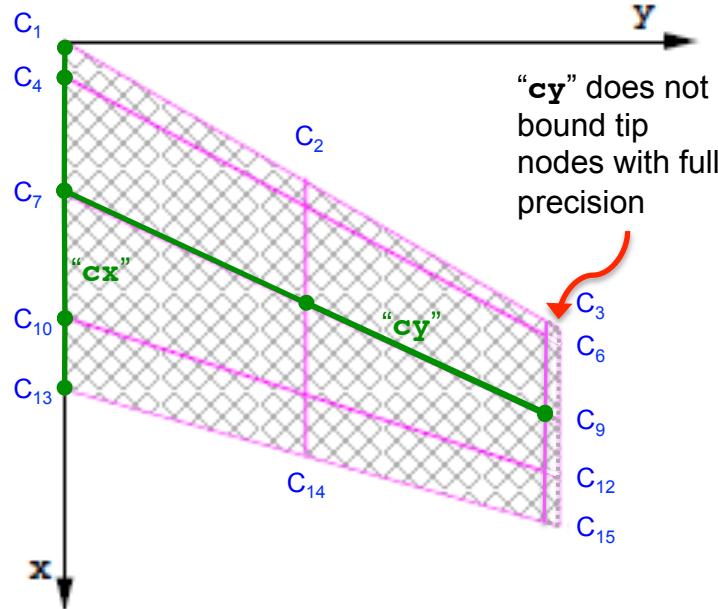
# What Could Go Wrong (1 of 2)

- Failure ... check “**GP.log**”
- Design locations must be defined to bound all target mesh nodes



# What Could Go Wrong (2 of 2)

- Design locations must be defined to bound all target mesh nodes



# MASSOUD User Defined Variables

- New variables as linear combination of MASSOUD variables

$$\frac{\partial \bar{R}}{\partial V_j} = \frac{\partial \bar{R}}{\partial P_i} \frac{\partial P_i}{\partial V_j}$$

$V_j$  MASSOUD Design Variables

$P_i$  User - Defined Design Variables

$$\begin{bmatrix} \frac{\partial P_1}{\partial V_1} & \frac{\partial P_2}{\partial V_1} & \dots & \frac{\partial P_{i_{\max}}}{\partial V_1} \\ \frac{\partial P_1}{\partial V_2} & \frac{\partial P_2}{\partial V_2} & \dots & \frac{\partial P_{i_{\max}}}{\partial V_2} \\ \vdots & \vdots & \vdots & \vdots \\ \frac{\partial P_1}{\partial V_{j_{\max}}} & \frac{\partial P_2}{\partial V_{j_{\max}}} & \dots & \frac{\partial P_{i_{\max}}}{\partial V_{j_{\max}}} \end{bmatrix}$$

$$P_1 = V_{10} - V_1 \quad (\text{Chord})$$

$$P_2 = (V_{10} + V_1)/2 \quad (\text{Mid - Chord Location})$$

$$P_3 = V_2 = V_{11}$$

	$P_1$	$P_2$	$P_3$
$V_1$	-1	0.5	0
$V_2$	0	0	1
$V_{10}$	1	0.5	0
$V_{11}$	0	0	1

M6.usd

```
# this is input sd file for MASSOUD
# number of row == number dvs within MASSOUD
# number of col == final number dvs
#(row) (col) (#of nonzero rows)
52 3 4
    d   1d   2d   3d
    1   -1   0.5   0
    2     0     0   1
    10   1   0.5   0
    11   0     0   1
```



# MASSOUD Pros and Cons

## Pros

- Consistent Meshes
- No need for mesh generation
- Easy to setup (hours)
- Parameterization is fast
- Analytic sensitivity
- Compact set of DVs
- Suitable for high- and low-fidelity application

## Cons

- Limited to small shape changes
- Fixed topology
- No built-in geometry constraints
- No direct CAD connection



# BandAids

- Aerodynamic Shape Parameterization based on Free-Form Deformation
- General application based on free-form deformation
  - Handles complex shapes
  - DVs are not classic aerodynamic parameters



<http://fun3d.larc.nasa.gov>

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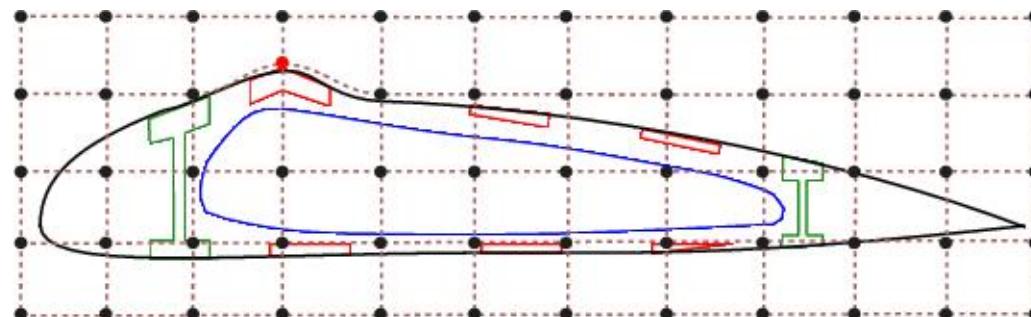
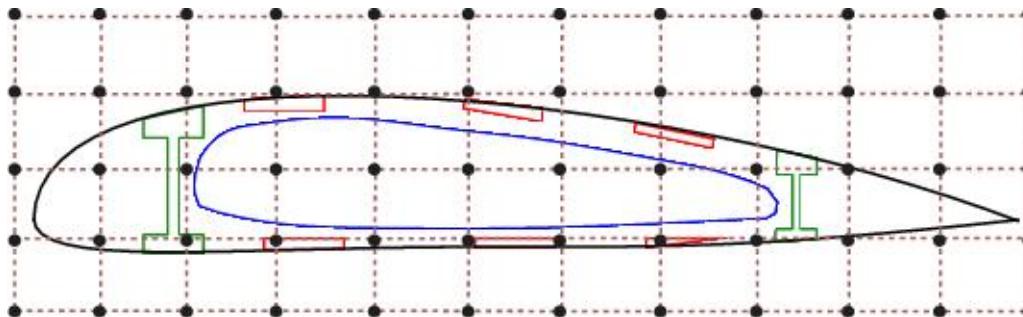
# BandAids Key Ideas

1. Parameterize surface mesh
  - Avoids mesh regeneration
2. Use FFD to represent shape perturbations
  - Automates surface parameterization
3. Parameterize changes in shape perturbation, not the shape itself
  - Reduces the number of design variables



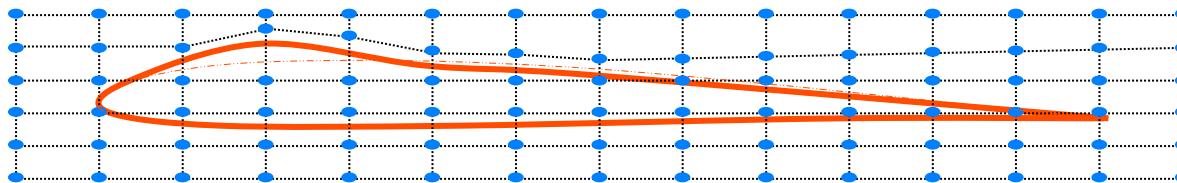
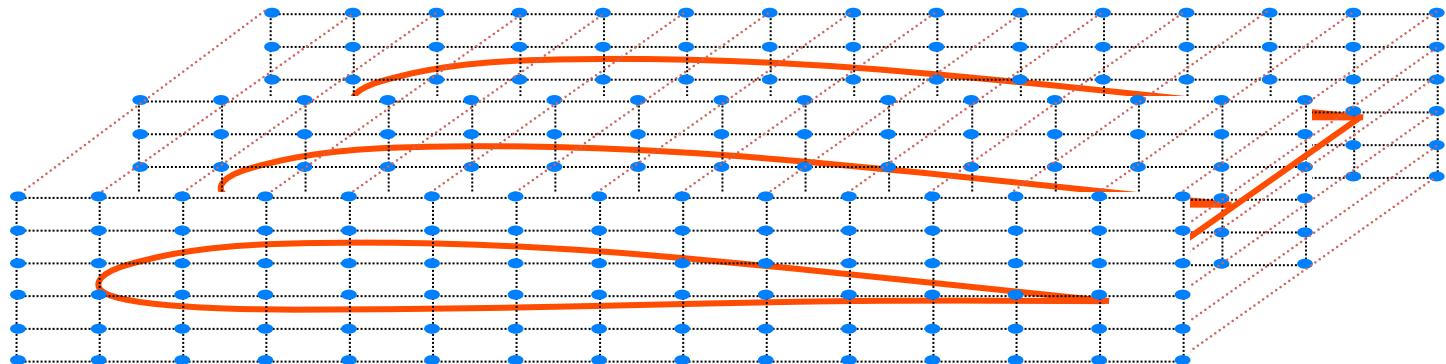
# BandAids FFD (1 of 3)

- Based on algorithm used in computer animation
  - Control points are DVs
  - Immersed in Jell-O®
- Design variables have no aerodynamic significance
  - Only those near surface have significant impact



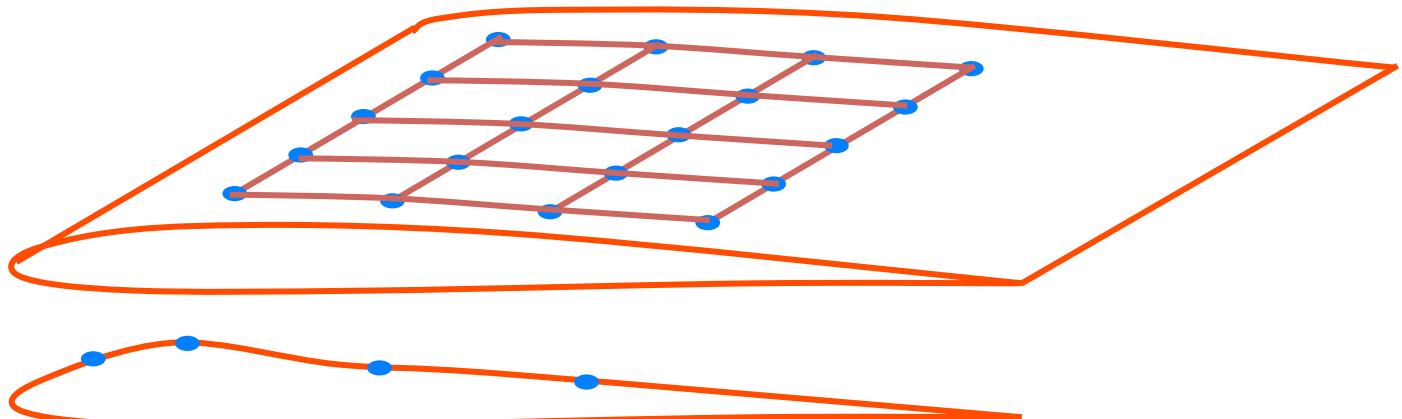
# BandAids FFD (2 of 3)

- Many more control points in 3D
  - Only those near surface have impact on surface



# BandAids FFD (3 of 3)

- Equivalent 3D bi-variant form of tri-varient FFD
  - Collapse CPs onto surface
    - Move CP moves surface underneath
  - Number of DVs reduced from  $N^3$  to  $N^2$
  - 4 sided *Bandaid* marking surface over geometry
    - Moves only surface to which it is collapsed
    - No MDO



# BandAids Parameterizes Changes

- Shape changes are small
  - Can be represented with fewer CPs than surface
- Maintains surface mesh character/quality

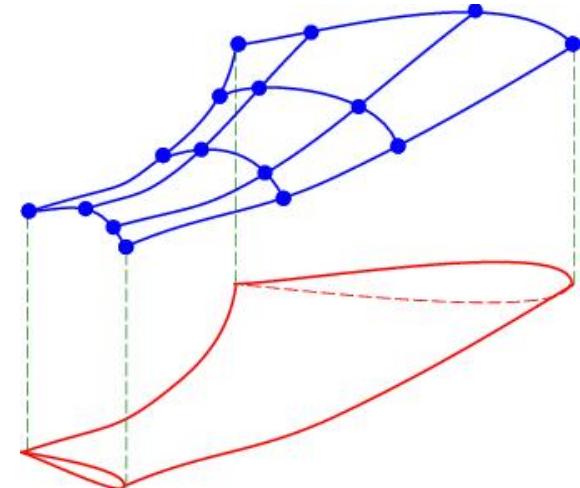
$$r_n(v) = r_n^b + \Delta r_n(v)$$

↑  
Surface mesh point  
Design variable vector

↑  
Baseline surface mesh

↑  
Shape changes

NURBS control points for camber & thickness



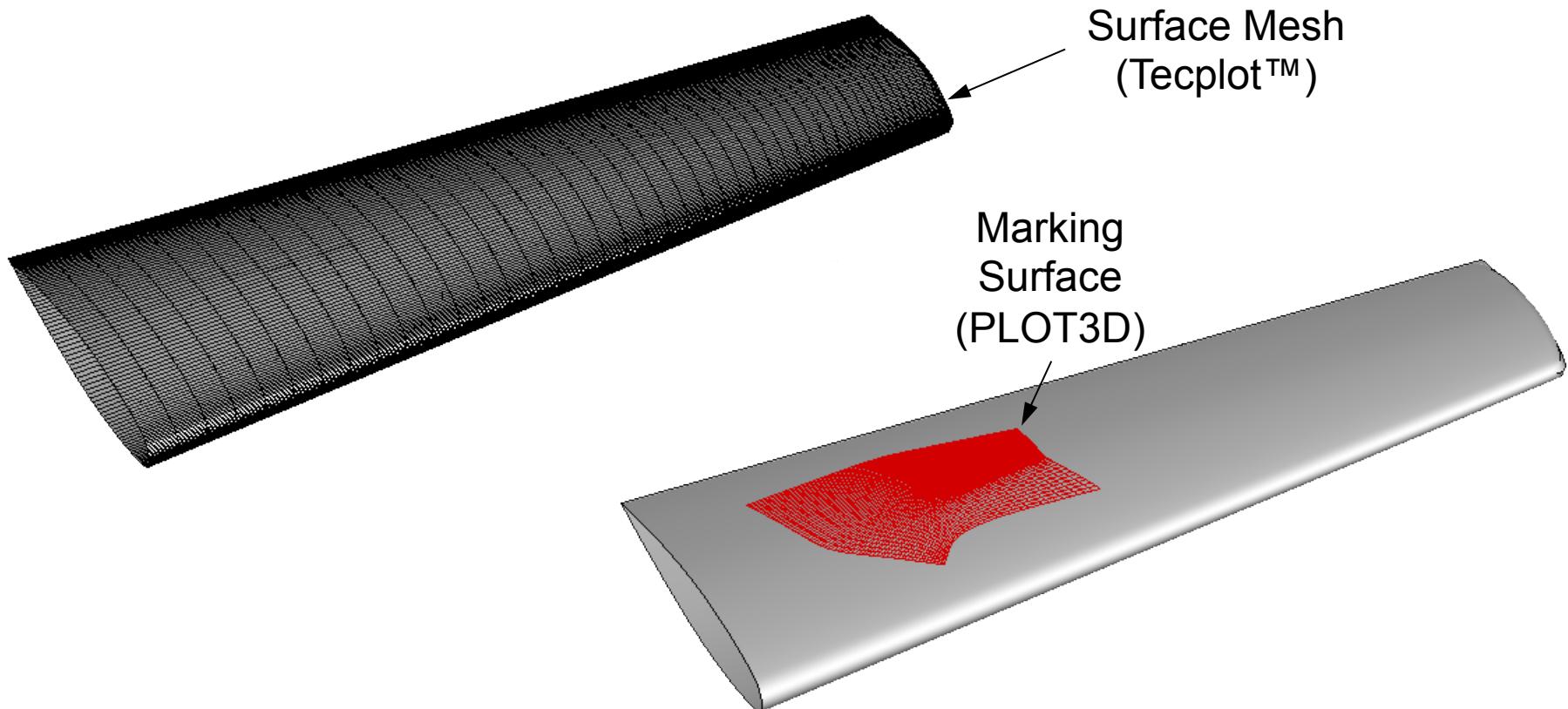
# BandAids Installation

- Distributed as source code
  - Single **Makefile** uses GNU C compiler (**gcc**)
    - Any localization must be done manually
  - Creates a single executable
    - `bandAids` parameterization and deformation



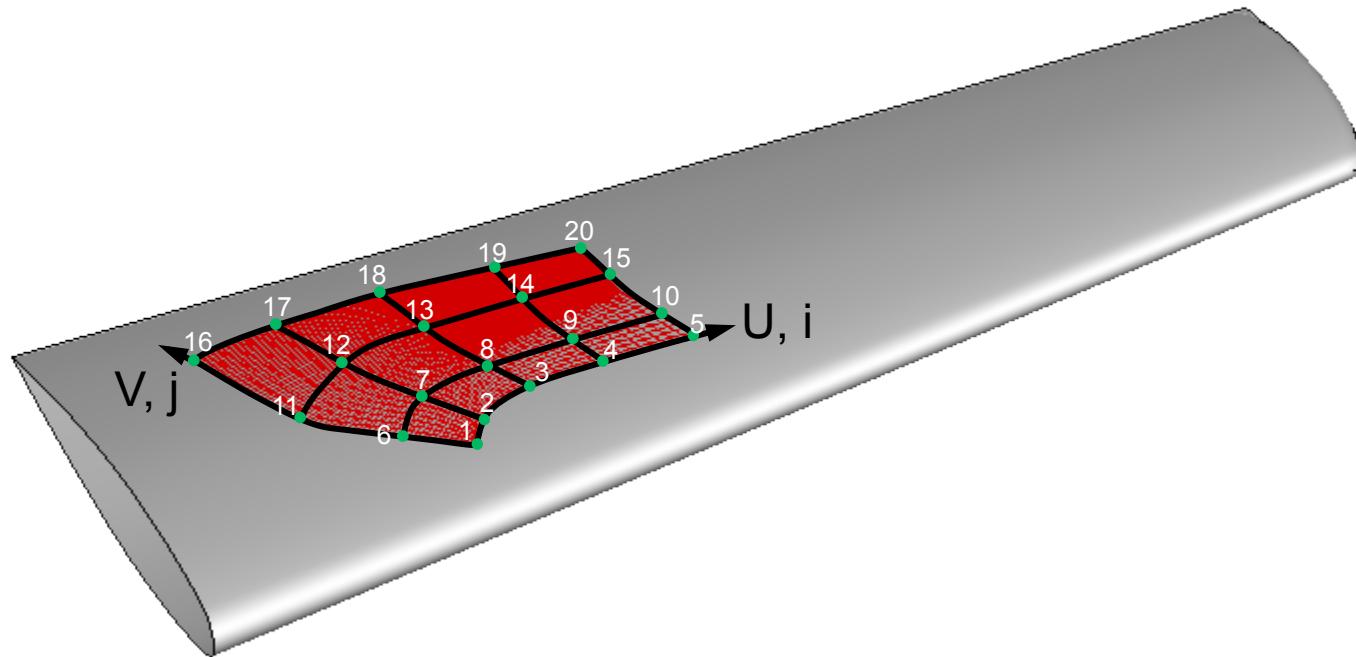
# BandAids Marking Surfaces (1 of 2)

- Create structured marking surface
  - Marks portion of geometry to parameterize
  - Can span multiple geometry surfaces



# BandAids Marking Surfaces (1 of 2)

- Marking surface interpolated by reference with  $n \times m$  CPs
  - $n \times m$  DVs



# BandAids Execution

```
% bandAids inMesh.plt \
    inDesignSurf.p3d \
    output \
    numDesignInU \
    numDesignInV \
    [tol]
```

- “**inMesh.plt**” target mesh in Tecplot™ format
- “**inDesignSurf.p3d**” marking surface in PLOT3D format
- “**outfile**” output file name prefix
- “**numDesignInU**” number of design variables in U-direction
- “**numDesignInV**” number of design variables in V-direction
- “**tol**” optional, max gap between mesh and marking surface



# BandAids Output

- Execution produces seven files:
  - “**output.bandaid**”
    - All non-zero shape information
    - Read directly by FUN3D
  - “**output.distance.plt**”
    - Tecplot™ file with the surface mesh including the distance between the surface mesh and marking surface
  - “**output.distanceSD.plt**”
    - Tecplot™ file containing surface mesh and sensitivity data
  - “**bandAidsSample.dvs**”
    - Template for input design variable file
  - “**bandAidsAll.usd**”, “**bandAidsCol.usd**”, and “**bandAidsRow.usd**”
    - Used for linking design variables



# BandAids Deformation

- Not necessary with FUN3D
  - Useful for validation
- Execute **bandAids** with **–deformMesh**

```
% bandAids -deformMesh \
      output.distanceSD.plt \
      my.dvs \
      new.plt
```
- “**output.distanceSD.plt**”
  - Tecplot™ file containing surface mesh and sensitivity data
- “**my.dvs**”
  - Input DV perturbations
- “**new.plt**”
  - Deformed surface mesh



# BandAids Results

- Visual inspection
  - Tecplot™
    - “**output.distanceSD.plt**” contains mesh and SDs
      - (e.g. XD1, YD1, ZD1... XDndv, YDndv, ZDndv)
  - GridTool
    - **% GridTool –d output.distanceSD.plt**
    - Sliders to interactively perturb DVs
    - Twist is non-linear and is only indication of change



# BandAids Pros and Cons

## Pros

- General Application
- Consistent Meshes
- No need for mesh generation
- Easy to setup (hours)
- Parameterization is fast
- Analytic sensitivity
- Compact set of DVs
- Suitable for high- and low-fidelity application

## Cons

- Non-intuitive DVs
- Limited to small shape changes
- No built-in geometry constraints
- No direct CAD connection



# What We Learned

- MASSOUD parameterizes with aerodynamic parameters
  - Best applied to aerodynamic shapes
- BandAids provides general application
  - Albeit w/o intuitive parameters
- Both mesh based parameterization
- Both tools parameterize shape changes not shape
  - Reduces number of DVs
- Both provide mesh perturbation with SDs suitable for FUN3D

